

# A correlated and positive model for Bayesian image deconvolution

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## Abstract

- Construction of a positive and correlated field by noise filtering.
- Application to a truncated Gaussian and a low-pass filter.
- Independent Metropolis-Hastings sampler to retrieve parameters.

## Keywords

Positivity, Correlation, Filtering, Metropolis-Hastings, High resolution

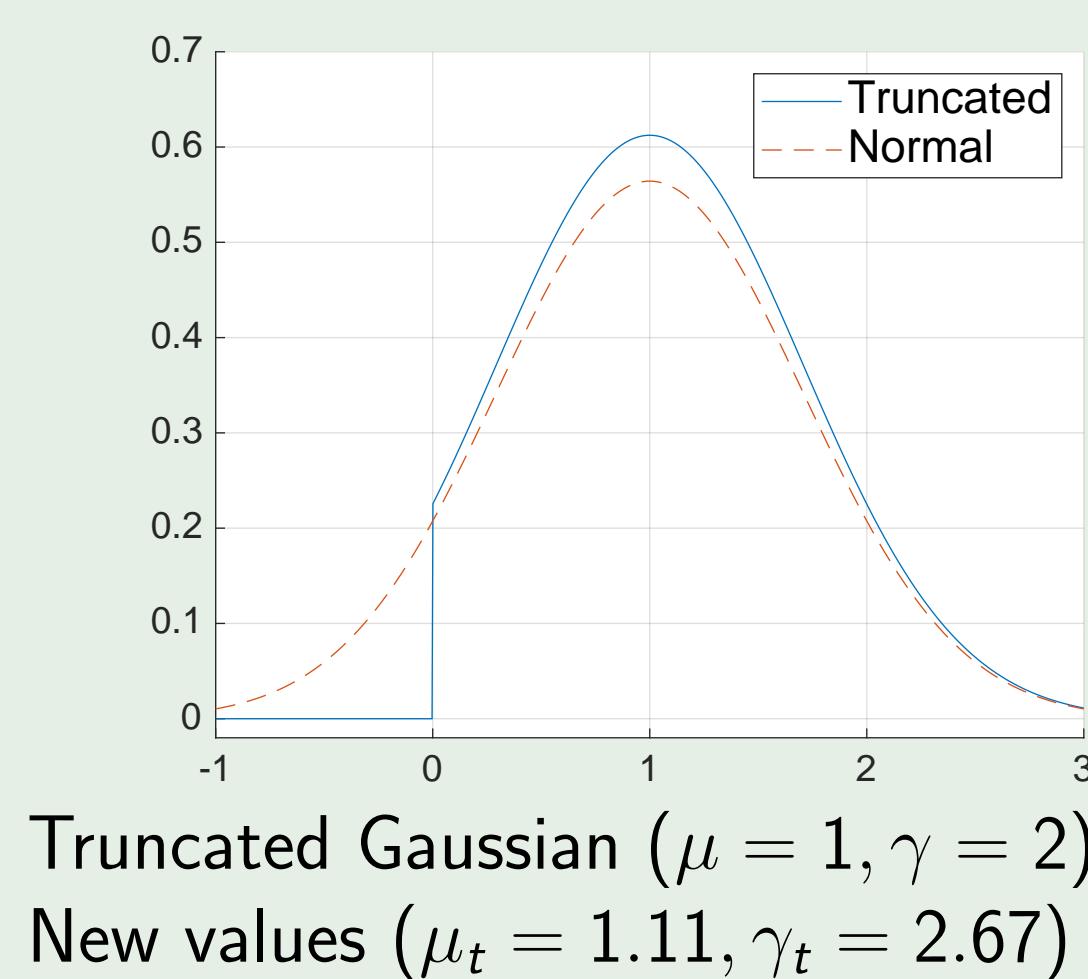
## Positive field

$U$  is a field with iid components according to a positive-support law

$$\mathbb{1}_+(\mathbf{u}) = \prod_{p=0}^{P-1} \mathbb{1}_{[0,+\infty)}(u_p) = \mathbb{1}_{\mathbb{R}_+^P}(\mathbf{u})$$

## Law for the components of $U$

- Uniform on  $[u_m, u_M]$  with  $u_m \geq 0$ 
  - + straightforward expression
  - bounded by  $u_M$
- Truncated Gaussian on  $0 \rightsquigarrow$  chosen
- Gamma
- Levy with  $\mu = 0$ 
  - + law stability after filtering
  - undefined moments



## Filtering

$A_\eta$  has positive coefficients

- preserves positivity
- adds correlation on the field  $U$

$$\mathbf{x} = A_\eta \mathbf{u}$$

$A_\eta$  controls the first and second order

$A_\eta$  represents a 2D convolution

- Mean :  $\mathbb{E}[X] = \mu_t \sum_{n_h, n_v} a_\eta(n_h, n_v)$
- Cov :  $C_X(n_h, n_v) = \gamma_t^{-1} a_\eta * a'_\eta(n_h, n_v)$
- PSD :  $S_X(\nu_h, \nu_v) = \gamma_t^{-1} |\hat{a}_\eta(\nu_h, \nu_v)|^2$
- $a_\eta(n_h, n_v)$  the impulsion resp.
- $\hat{a}_\eta(\nu_h, \nu_v)$  the frequency resp.

$A_\eta$  has usefull properties

- Circulant Block-Toeplitz with Circulant Blocks (CBTCB)
- Diagonalisable in the Fourier domain
  - $F$  is the matrix of the discretised 2D Fourier transform
  - $\Lambda_\eta$  is the discretised frequency response of the filtering

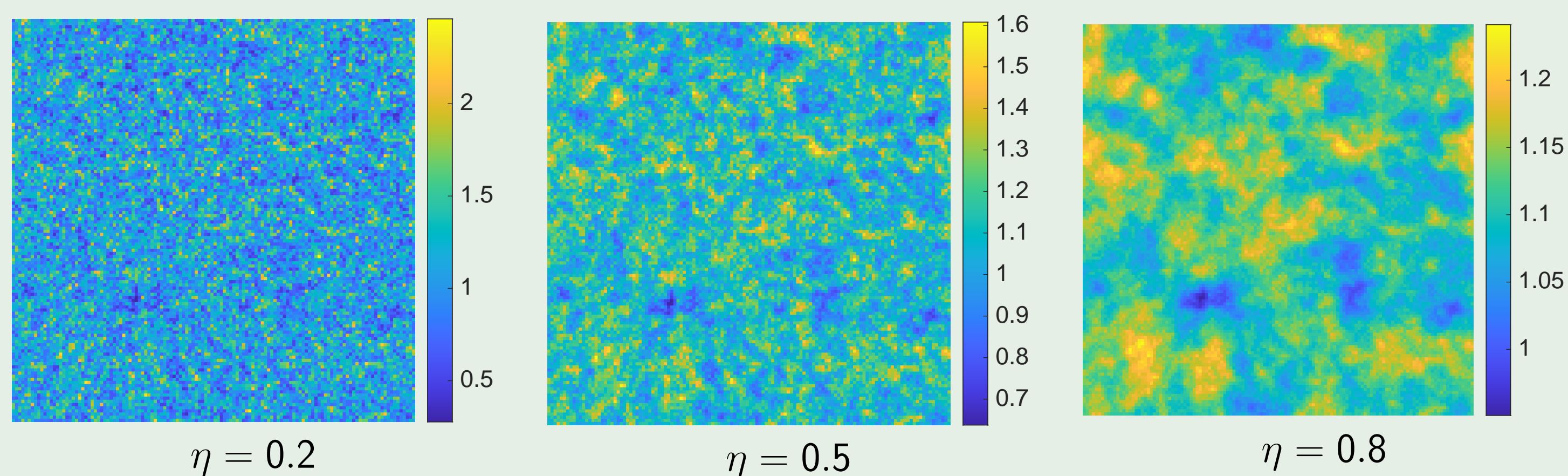
$$\Lambda_\eta = F A_\eta F^\dagger = \text{diag}[\lambda_\eta(p), p = 0 \dots (P-1)]$$

$$F \mathbf{x} = \hat{\mathbf{x}} = \Lambda_\eta \hat{\mathbf{u}} = \Lambda_\eta F \mathbf{u}$$

with  $\lambda_\eta(p) = \hat{a}_\eta(n_h/N, n_v/N)$  the discretised frequency response.

## Example of images

$$S_X(\nu_h, \nu_v) = \gamma_t^{-1} \times (1 - \eta)^2 \left[ 1 + \eta^2 - 2\eta \cos \left( 2\pi \sqrt{\nu_h^2 + \nu_v^2} \right) \right]^{-1}$$



## Change of variables

Filtering corresponds to a multivariate change of variables.

$$\begin{aligned} f_X(\mathbf{x}) &= |\det A_\eta|^{-1} f_U(A_\eta^{-1} \mathbf{x}) \mathbb{1}_+(A_\eta^{-1} \mathbf{x}) \\ &= |\det \Lambda_\eta|^{-1} f_U(F^\dagger \Lambda_\eta^{-1} \hat{\mathbf{x}}) \mathbb{1}_+(F^\dagger \Lambda_\eta^{-1} \hat{\mathbf{x}}) \end{aligned}$$

## Filtered truncated Gaussian case

$$\begin{aligned} f_{X|\Theta}(\mathbf{x}|\boldsymbol{\theta}) &= |\det A_\eta|^{-1} K^P \exp \left( -\frac{\gamma}{2} \|A_\eta^{-1} \mathbf{x} - \mu \mathbb{1}\|^2 \right) \mathbb{1}_+(A_\eta^{-1} \mathbf{x}) \\ &= |\det \Lambda_\eta|^{-1} K^P \exp \left( -\frac{\gamma}{2} \sum_{p=0}^{P-1} \left| \frac{\hat{x}_p}{\lambda_\eta(p)} - \mu \hat{\mathbb{1}}_p \right|^2 \right) \mathbb{1}_+(F^\dagger \Lambda_\eta^{-1} \hat{\mathbf{x}}) \end{aligned}$$

- $\boldsymbol{\theta} = [\mu, \gamma, \eta]$  the parameter vector
- $K$  the partition function of  $U$

$$K = \sqrt{\frac{\gamma}{2\pi}} \times \frac{2}{1 + \text{erf}(\sqrt{\frac{\gamma}{2}} \mu)}$$

- $\mu$  the mean before the truncation of  $U$
- $\gamma$  the precision (inverse variance) before the truncation of  $U$

## Estimation of parameters

Given a direct observation of  $X$ , we aim to estimate  $\boldsymbol{\theta} = [\mu, \gamma, \eta]$

$$\pi_{\Theta|X}(\boldsymbol{\theta}|x) = \frac{f_{X|\Theta}(x|\boldsymbol{\theta}) \pi_{\Theta}(\boldsymbol{\theta})}{\int_{\Theta} f_{X,\Theta}(x, \boldsymbol{\theta}) d\boldsymbol{\theta}}$$

- $\pi_{\Theta|X}$  the posterior describing our problem
- $f_{X|\Theta}$  the likelihood (filtered and truncated Gaussian)
- $\pi_{\Theta}$  the prior knowledge about the parameters
- $\int_{\Theta} f_{X,\Theta}(x, \boldsymbol{\theta}) d\boldsymbol{\theta}$  the normalising constant

Uniform and independent priors are considered for  $\boldsymbol{\theta}$ .

## Independent Metropolis-Hastings

Sampling  $\pi_{\Theta|X}$  using a Metropolis-Hastings does not require  $\int_{\Theta} f_{X,\Theta}(x, \boldsymbol{\theta}) d\boldsymbol{\theta}$ .

$$\pi_{\Theta|X}(\boldsymbol{\theta}|x) \propto f_{X|\Theta}(x|\boldsymbol{\theta}) \pi_{\Theta}(\boldsymbol{\theta})$$

By using prior distribution as the proposed law, only the (log-)posterior is needed.

$$\begin{aligned} LP(\boldsymbol{\theta}) &= - \sum_{p=0}^{P-1} \log(|\lambda_\eta(p)|) + P \log(K) - \frac{\gamma}{2} \sum_{p=0}^{P-1} \left| \frac{\hat{x}_p}{\lambda_\eta(p)} - \mu \hat{\mathbb{1}}_p \right|^2 \\ &\quad + \log(\mathbb{1}_{[\mu_m, \mu_M] \times [0, \gamma_M] \times [\eta_m, \eta_M]}(\boldsymbol{\theta})) \\ &\quad + \log(\mathbb{1}_+(F^\dagger \Lambda_\eta^{-1} \hat{\mathbf{x}})) \end{aligned}$$

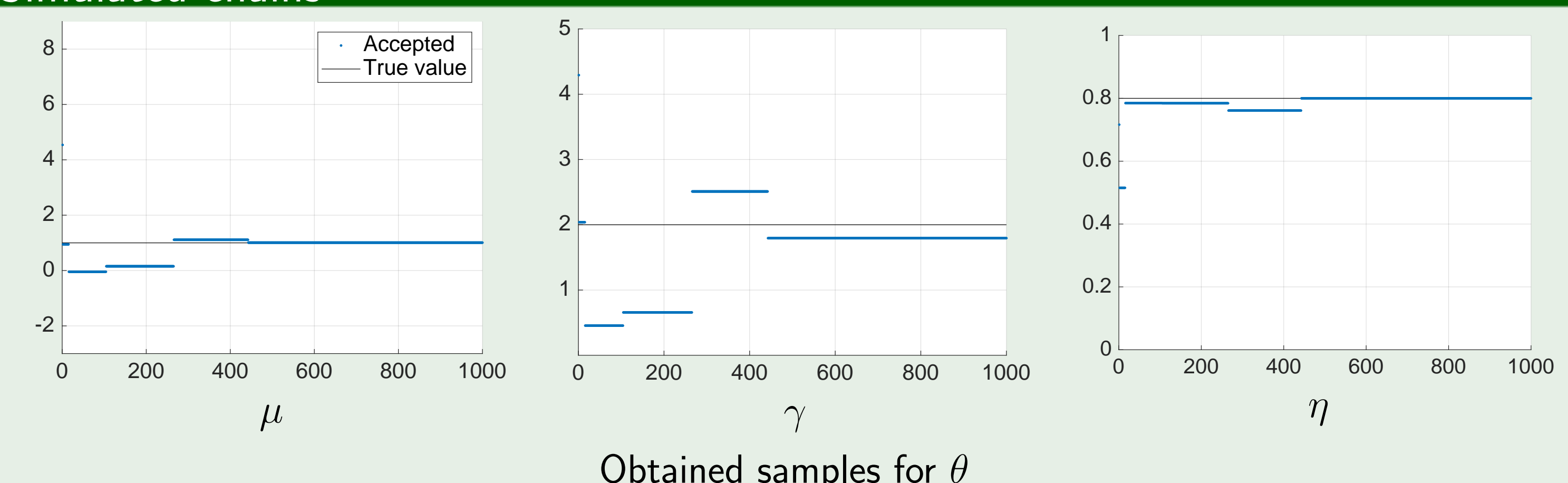
## Pseudo code

```

1: repeat
2:   Sample  $\boldsymbol{\theta}_0$  from  $\pi_{\Theta}$ 
3: until  $\mathbb{1}_+(F^\dagger \Lambda_{\eta_0}^{-1} \hat{\mathbf{x}}) = 1$ 
4: for  $k = 1$  to  $K$  do
5:   Sample  $\boldsymbol{\theta}^p$  from  $\pi_{\Theta}$ 
6:   if  $\mathbb{1}_+(F^\dagger \Lambda_{\eta^p}^{-1} \hat{\mathbf{x}}) = 0$  do
7:      $\boldsymbol{\theta}_k = \boldsymbol{\theta}_{k-1}$ 
8:   else
9:     Compute acceptance ratio  $\alpha = \exp(\min(0, LP(\boldsymbol{\theta}^p) - LP(\boldsymbol{\theta}_{k-1})))$ 
10:    Sample  $u$  from Uniform(0, 1)
11:    if  $u < \alpha$  do
12:       $\boldsymbol{\theta}_k = \boldsymbol{\theta}^p$ 
13:    else
14:       $\boldsymbol{\theta}_k = \boldsymbol{\theta}_{k-1}$ 
15:    end if
16:  end if
17: end for

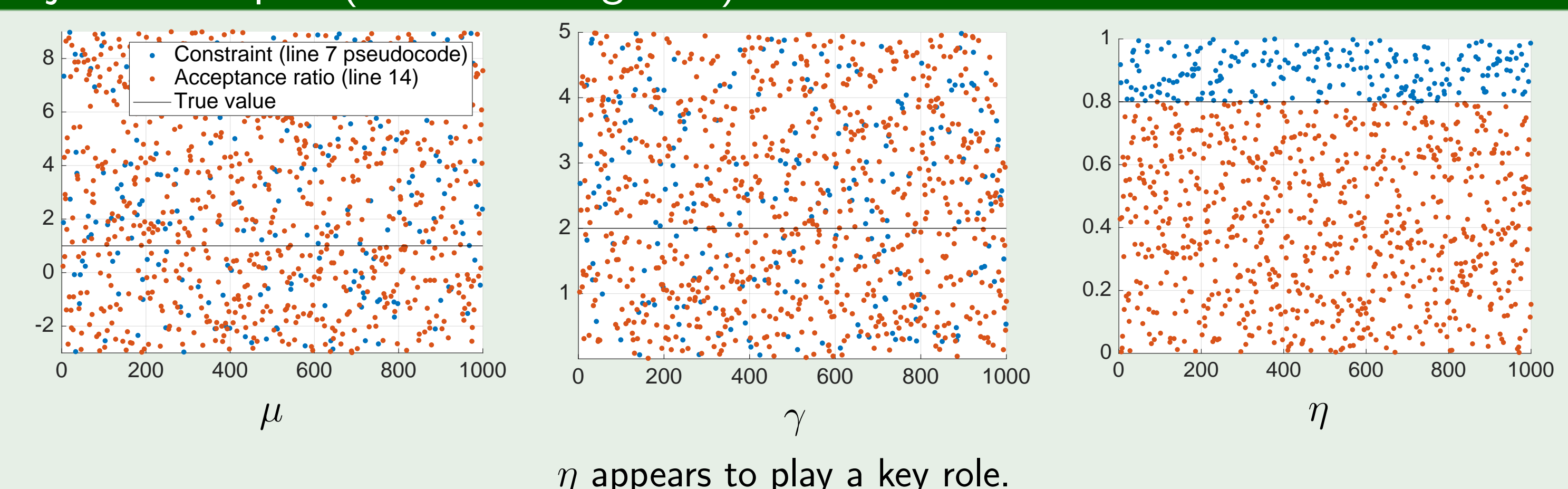
```

## Simulated chains



Issue: low acceptance rate (0.6%)  $\rightsquigarrow$  lack of diversity.

## Rejected samples (under investigation)



$\eta$  appears to play a key role.

## Perspectives

- Analysing  $\mathbb{1}_+(F^\dagger \Lambda_{\eta^p}^{-1} \hat{\mathbf{x}}) = \mathbb{1}_+(F^\dagger \Lambda_{\eta^p}^{-1} \Lambda_{\eta^*} \hat{\mathbf{u}}) \rightsquigarrow$  new filter  $\Lambda_{\eta^p}^{-1} \Lambda_{\eta^*}$
- Random Walk Metropolis  $\boldsymbol{\theta}^p = \boldsymbol{\theta}_{k-1} + \varepsilon$  with  $\varepsilon \sim \mathcal{N}(0, \sigma^2 I)$
- Another filtering:  $\mathbf{x} = \frac{1}{\sqrt{\alpha}} A_\eta \mathbf{u} + \beta \mathbb{1}$  (with  $\mu = 0$  and  $\gamma = 1$ )
- Application to images in the astronomical, medical or industrial field.

## Bibliography

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